

(11) Today

4.3 Character Tables

4.4 Uses of Character Tables

Next Class (12)

4.4 Uses of Character Tables

Second Class from Today

Test 1 on Chap 1 through Chap 4 section 4.2
(symmetry operations and finding Point Groups)

Third Class from Today (13)

4.4 Uses of Character Tables

operations

functions

labels

characters

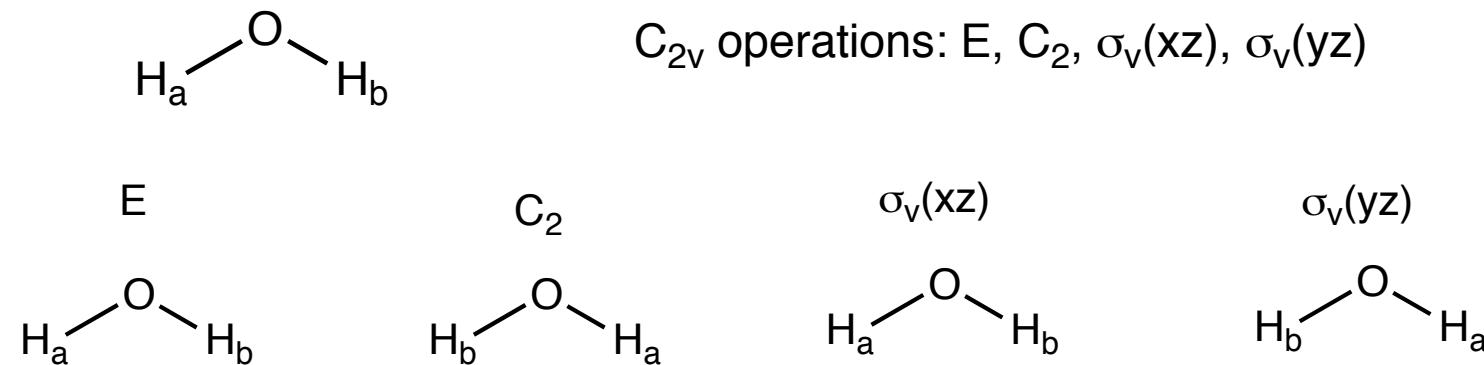
classes

C_{2v}	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$		
A_1	1	1	1	1	z	x^2, y^2, z^2
A_2	1	1	-1	-1	R_z	xy
B_1	1	-1	1	-1	x, R_y	xz
B_2	1	-1	-1	1	y, R_x	yz

a summary of all of the symmetry in a
given point group

Ways of Representing Symmetry Operations

Section 4.3



Matrix representations

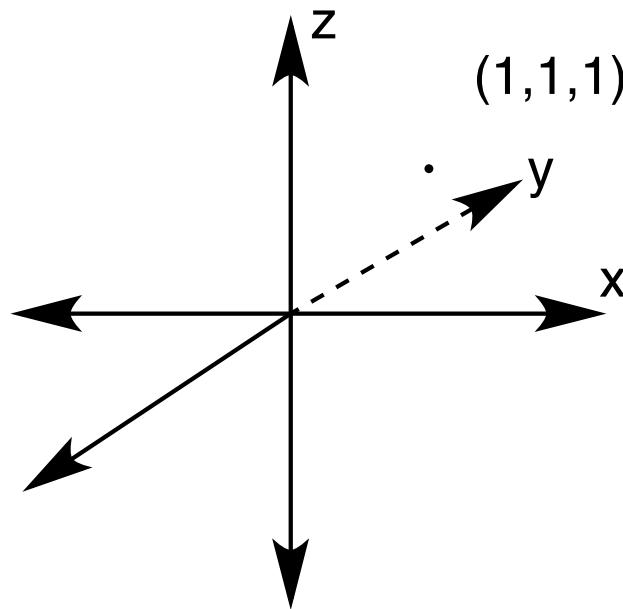
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
 \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
 \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
 \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

1x1 transformation matrices for each individual axis

1	-1	1	-1	x
1	-1	-1	1	y
1	1	1	1	z

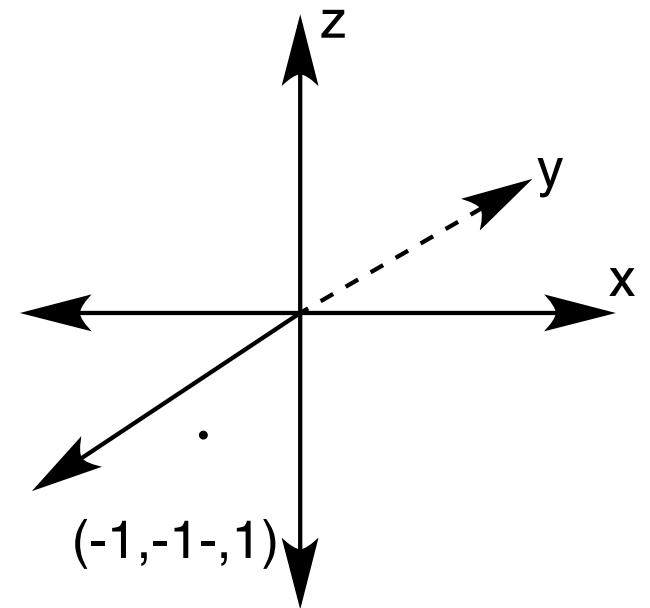
The traces of the 3x3 transformation matices

3	-1	1	1
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i

A horizontal double-headed arrow positioned between the two coordinate systems, with the letter i centered above it, representing a transformation or mapping from the initial state to the final state.



$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} \quad \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

Matrix Multiplication...

Section 4.3

Number of columns in the first matrix must equal number of rows in the second

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

new x value = sum of Row 1 x Column 1

new y value = sum of Row 2 x Column 1

new z value = sum of Row 3 x Column 1

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} -1(x) + 0(y) + 0(z) \\ 0(x) + -1(y) + 0(z) \\ 0(x) + 0(y) + -1(z) \end{bmatrix}$$

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} -x \\ -y \\ -z \end{bmatrix}$$

C_{2v}	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$		
A ₁	1	1	1	1	z	x^2, y^2, z^2
A ₂	1	1	-1	-1	R_z	xy
B ₁	1	-1	1	-1	x, R_y	xz
B ₂	1	-1	-1	1	y, R_x	yz

1x1 transformation matrices for each individual axis in the C_{2v} point group

4	1	-1	1	-1	x
*	1	-1	-1	1	y
Δ	1	1	1	1	z

C_{2v}	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$		
A_1	1	1	1	1	z	x^2, y^2, z^2
A_2	1	1	-1	-1	R_z	xy
B_1	1	-1	1	-1	x, R_y	xz
B_2	1	-1	-1	1	y, R_x	yz

Mulliken symbols
 Irreducible
 Symmetric

Summary symmetry for each
 representation

antisymmetric - thing doesn't move but its
 sign changes (phase of p orbital
 dir)

C_{2v}	E	C_2	$\sigma_v(xz)$	$\sigma_v(yz)$		
A_1	1	1	1	1	z	x^2, y^2, z^2
A_2	1	1	-1	-1	R_z	xy
B_1	1	-1	1	-1	x, R_y	xz
B_2	1	-1	-1	1	y, R_x	yz

A Symmetric w.r.t. principle axis

B antisymmetric w.r.t. principle axis

subscript 1 is for representations that are symmetric w.r.t. a C_2 that is perpendicular to the principle axis

subscript 2 is for representations that are antisymmetric w.r.t. a C_2 that is perpendicular to the principle axis

in the absence of a C_2 a vertical mirror plane perpendicular to the plane of the molecule is used instead

subscript g symmetric w.r.t. inversion

subscript u antisymmetric w.r.t. inversion

' symmetric w.r.t. σ_h

" antisymmetric w.r.t. σ_h

How do we use Character Tables.

To examine the symmetry of the thing we are interested in (molecular motions, orbitals, symmetry adapted linear combinations of atomic orbitals...) we create a reducible representation of the symmetry operations of the motions.

We use linear algebra to determine the irreducible representations that must be combined to form the reducible one that we just found.

We use the functions in the character tables to interpret our results.

For each operation and each item add 1, 0 or -1 to the value for χ based on whether there is no change (1), the items changes position (0), or doesn't change position but changes sign (-1).

Number of IR Active Vibrational Modes for Water

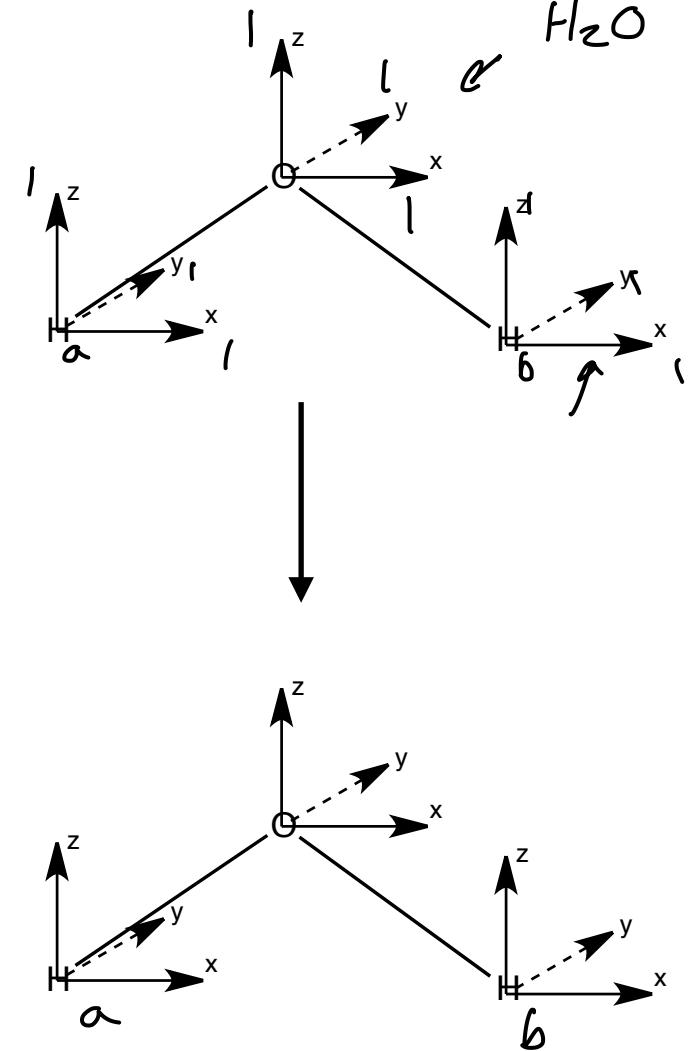
Find this by analyzing all possible motions of the atoms in

Section 4.4

C_{2v}	E	C_2	$\sigma_{(xz)}$	$\sigma_{(yz)}$
	9			

$$\begin{matrix}
 & \begin{matrix} x'_o \\ y'_o \\ z'_o \end{matrix} & = & \begin{matrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} & \begin{matrix} x_o \\ y_o \\ z_o \end{matrix} \\
 H_a \begin{matrix} x'_{Ha} \\ y'_{Ha} \\ z'_{Ha} \end{matrix} & = & \begin{matrix} 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \end{matrix} & \begin{matrix} x_{Ha} \\ y_{Ha} \\ z_{Ha} \end{matrix} \\
 H_b \begin{matrix} x'_{Hb} \\ y'_{Hb} \\ z'_{Hb} \end{matrix} & = & \begin{matrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{matrix} & \begin{matrix} x_{Hb} \\ y_{Hb} \\ z_{Hb} \end{matrix}
 \end{matrix}$$

Summarize this matrix using its trace 9 which is the sum of the diagonal

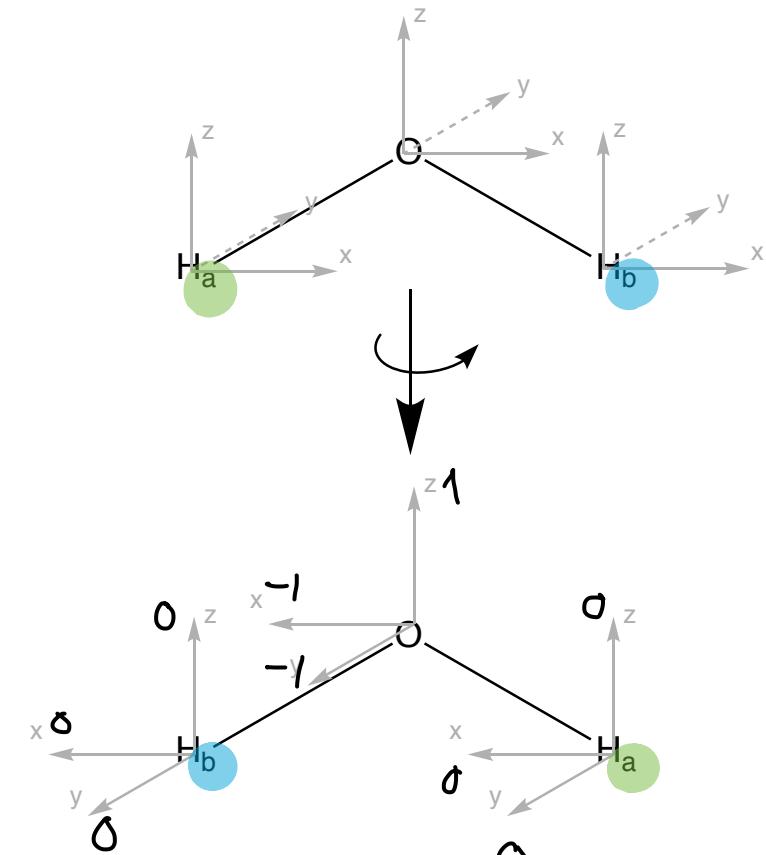


Number of IR Active Vibrational Modes for Water

Section 4.4

C_{2v}	E	C_2	$\sigma_{(xz)}$	$\sigma_{(yz)}$
	9	-1		

$$\begin{array}{l}
 \text{O} \quad x'_0 \quad | \quad -1 \quad 0 \\
 \text{y}'_0 \quad 0 \quad -1 \quad 0 \\
 \text{z}'_0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \\
 H_a \quad x'_{Ha} \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \\
 y'_{Ha} \quad 0 \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \quad 0 \quad 0 \quad -1 \\
 z'_{Ha} \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \quad 0 \quad 1 \\
 H_b \quad x'_{Hb} \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \\
 y'_{Hb} \quad 0 \quad 0 \quad 0 \quad 0 \quad -1 \quad 0 \quad 0 \quad 0 \quad 0 \\
 z'_{Hb} \quad 0 \quad 0 \quad 0 \quad 0 \quad 0 \quad 1 \quad 0 \quad 0 \quad 0
 \end{array} = \begin{array}{l}
 x_0 \quad y_0 \quad z_0 \quad X_{Ha} \quad Y_{Ha} \quad Z_{Ha} \quad X_{Hb} \quad Y_{Hb} \quad Z_{Hb}
 \end{array}$$



$$\text{trace} = -1$$

Create the characters for the
reducible representation for all the
possible motions

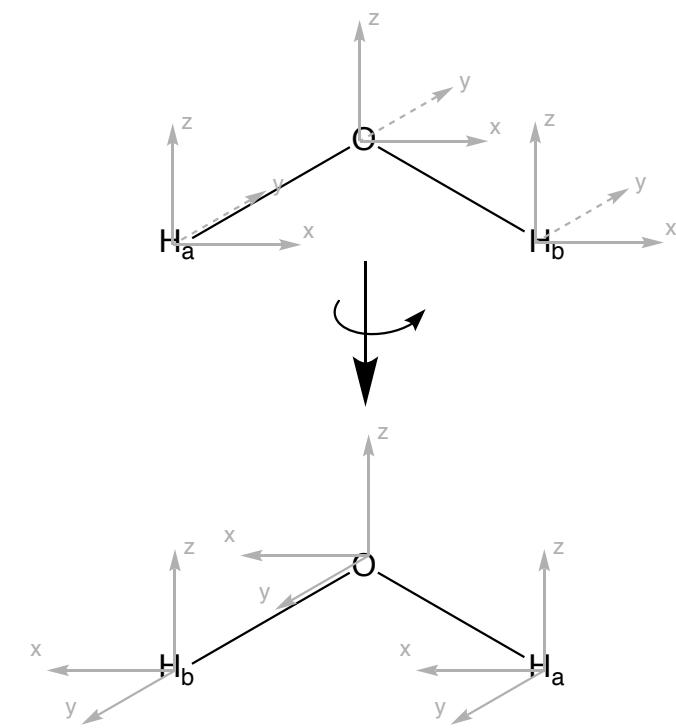
did it change position no
did it change sign or direction
add 1 for each
vector that did nothing

Easier way to determine the trace?

Section 4.4

C_{2v}	E	C_2	σ_{xz}	σ_{yz}
	9			

O	x'_o	-1			x_o
	y'_o		-1		y_o
	z'_o			1	z_o
H_a	x'_{Ha}		0	-1	x_{Ha}
	y'_{Ha}		0	-1	y_{Ha}
	z'_{Ha}		0	1	z_{Ha}
H_b	x'_{Hb}	-1	0		x_{Hb}
	y'_{Hb}	-1	0		y_{Hb}
	z'_{Hb}	1	0	0	z_{Hb}



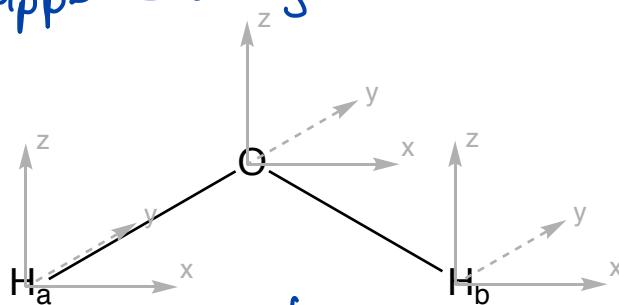
For each operation add 1, 0 or -1 to the value for χ based on whether there is no change (1), the items changes position (0), or doesn't change position but changes sign (-1).

Number of IR Active Vibrational Modes for Water

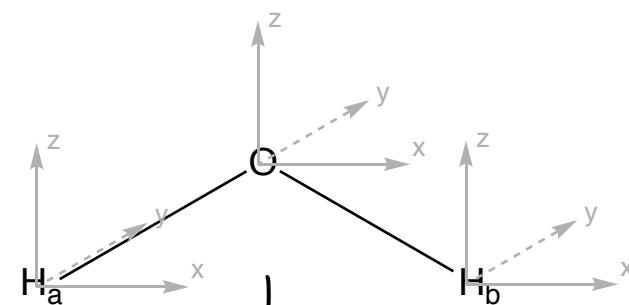
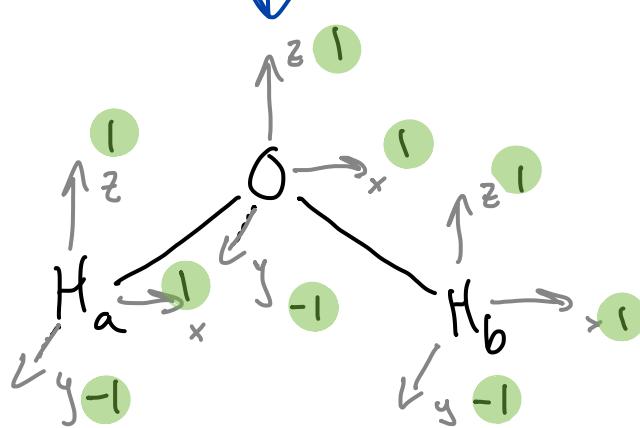
Section 4.4

C_{2v}	E	C_2	$\sigma(xz)$	$\sigma(yz)$
Γ	9	-1	3	1

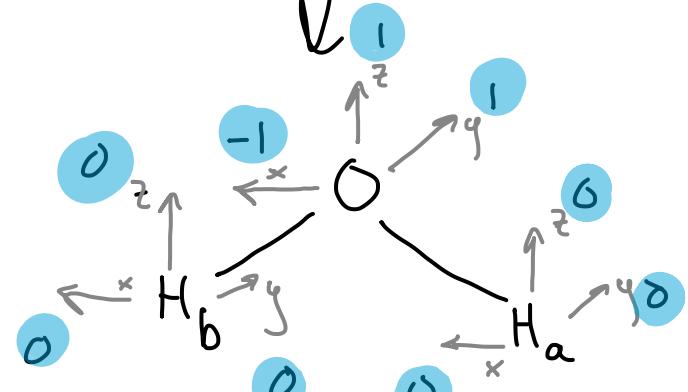
upper case gamma



$\delta(xz)$



$\sigma(yz)$



For each operation add 1, 0 or -1 to the value for χ based on whether there is no change (1), the items changes position (0), or doesn't change position but changes sign (-1).